# Invariant Measure of Quantum Trajectories 

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work in collaboration with
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## Plan of the talk

.1) Generalities
. 2) Invariant measure
.3) Speed of convergence

# 1) Generalities 

(1) Definition-First properties
(2) Link with other works
(3) Examples

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## Framework

- Let $\mathcal{H}_{S}=\mathbb{C}^{k}$ be the space describing the quantum system $\mathcal{S}$
- Let $\mathcal{D}(\mathcal{S})$ be the set of density matrices on $\mathcal{S}$, that is

$$
\mathcal{D}(\mathcal{S})=\left\{\rho \in \mathcal{B}\left(\mathbb{C}^{k}\right) \text {, s.t, } \rho \geqslant 0, \operatorname{tr}(\rho)=1\right\}
$$

$\Rightarrow$ The rank one projectors belonging to $\mathcal{D}(\mathcal{S})$ represent the pure states.

- We denote by $\left(\rho_{п}\right)$ the Markov chain describing the evolution of $\mathcal{S}$ undergoing repeated indirect measurements. If $\rho_{n}=\rho$ then $\rho_{n+1}$ can takes $\ell$ different values

$$
\rho_{n+1}(i)=\frac{V_{i \rho} V_{i}^{*}}{\operatorname{tr}\left(V_{i \rho} \rho V_{i}^{*}\right)}
$$

with probability $\operatorname{tr}\left(V_{i} \rho V_{i}^{*}\right)$.

- The sequence $\left(\rho_{n}\right)$ is called a quantum trajectory.


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## First properties

- Expectation: Let $\mathcal{S}_{n}$ be the natural filtration of $\left(\rho_{n}\right)$, that is $\mathcal{S}_{n}=\sigma\left(\rho_{1}, \ldots, \rho_{n}\right)$, we have

$$
\mathbb{E}\left[\rho_{n+1} \mid \mathcal{S}_{n}\right]=\phi\left(\rho_{n}\right),
$$

where

$$
\phi(\rho)=\sum_{i=1}^{\ell} V_{i} \rho V_{i}^{*}
$$

The map $\phi$ is a completely positive and trace preserving map (CPTP) which describes the evolution of $\mathcal{S}$ without measurement. In particular

$$
\mathbb{E}\left[\rho_{n}\right]=\phi^{n}\left(\rho_{0}\right) .
$$

- Pure states: If $\rho_{0}=\left|x_{0}\right\rangle\left\langle x_{0}\right|$ is a pure state, then there exists $\left(x_{n}\right)$ such that $\rho_{n}=\left|x_{n}\right\rangle\left\langle x_{n}\right|$. If $x_{n}=x$ then $x_{n+1}$ can takes $\ell$ different values



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$$
x_{n+1}=\frac{V_{i x}}{\| V_{i x} x}, i=1, \ldots, \ell
$$

with probability $\left\|V_{i x} x\right\|^{2}=\operatorname{tr}\left(V_{i}|x\rangle\langle x| V_{i}^{*}\right)$

## Purification

- Pur: The only projectors $Q$ statisfying $Q V_{i}^{*} V_{i} Q=\lambda_{i} Q, i=1, \ldots, \ell$ are rank one projectors.
- Under this condition, we have the following theorem due to H. Maassen and B. Kümmerer


## Theorem

Assume (Pur). The Markov chain $\left(\rho_{n}\right)$ purifies in the sense that for all $k \in \mathbb{N}^{*}$

$$
\lim _{n \rightarrow \infty} \operatorname{tr}\left(\rho_{n}^{k}\right)=1
$$

- Note that $\operatorname{tr}\left(\rho^{2}\right)=1$ implies that $\rho$ is a pure state
- Under (Pur) one can show that there exists $\left(y_{n}\right)$ such that

$$
\lim _{n \mapsto \infty} \| \rho_{n}-\left|y_{n}\right\rangle\left\langle y_{n}\right| \|=0
$$

## Existence of an invariant measure

- In the sequel we shall always assume (Pur). Then one can restrict the study of the problem of invariant measure to the set of pure states.
- The set of pure states is isomorphic to $P\left(\mathbb{C}^{k}\right)$ the projective space over $\mathbb{C}^{k}$. For any non zero $x \in \mathbb{C}^{k}$, we denote $\hat{x}$ it's representent on $P\left(\mathbb{C}^{k}\right)$
- In order to simplify the notation we put $A \cdot \hat{x}=\widehat{A \hat{x}}$ when $\|A \hat{x}\| \neq 0$


## Definition

The Markov kernel describing the quantum trajectory attached to $\left\{V_{i}, i=1, \ldots, \ell\right\}$ is:

$$
\Pi(\hat{x}, A)=\sum_{i=1}^{\ell} \mathbf{1}_{A}\left(V_{i} \cdot \hat{x}\right)\left\|V_{i} \hat{x}\right\|^{2},
$$

for all Borel set $A$ of $P\left(\mathbb{C}^{k}\right)$.

## Existence of an invariant measure

- Note that the Markov kernel $\pi$ is Feller, that is it maps continuous functions into continuous functions.

$$
\begin{aligned}
\Pi f(\hat{x}) & =\int_{P\left(\mathbb{C}^{k}\right)} f(\hat{y}) \Pi(\hat{x}, d \hat{y}) \\
& =\sum_{i=1}^{\ell} f\left(V_{i} \cdot \hat{x}\right)\left\|V_{i} \hat{x}\right\|^{2}=\sum_{i=1}^{\ell} f\left(\frac{V_{i} \hat{x}}{\left\|V_{i} \hat{x}\right\|}\right)\left\|V_{i} \hat{x}\right\|^{2}
\end{aligned}
$$

- Note that this Markov kernel is not strongly Feller.
- Denote Inv the set of invariant measure of $\Pi(\nu \Pi=\nu)$


## Proposition <br> Since the Markov kernel is Feller and the set $P\left(\mathbb{C}^{k}\right)$ is compact, we can apply the Markov Kakutani Theorem to conclude that Inv is non-empty.

- Question: Do we have uniqueness of invariant measure and do we have convergence towards this invariant measure?


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stochastic differential equation for quantum states" Infin. Dimens. Anal Quantum. Probab. Relat. Top. 06, 223 (2003)
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## Products of random matrices

- Recall that the quantum trajectory can be defined as

$$
\hat{x}_{n}=V_{i_{n}} \ldots V_{i_{1}} \cdot \hat{x}_{0}
$$

In some sense we can summarize the quantum trajectory through the product of random matrices $V_{i_{n}} \ldots V_{i_{1}}$

- This is exactly the setup of product of random matrices developed by

Guivarc'h, A. Raugi, E. Lepage, P. Bougerol, J. Lacroix.... "Products of Random Matrices with Applications to Schrödinger Operators" (book by P. Bougerol and J. Lacroix)

- In this setup the main assumptions are
(a) The matrices $V_{i}$ are invertible
(2) The matrices $V_{i}$ are i.i.d (extended to Markovian dependance) (3) The matrices $V_{i}$ are strongly irreducible, there is no $\cup_{i=1}^{p} E_{i}$ such that

$$
V_{j} \cup_{i=1}^{p} E_{i}=\cup_{j=1}^{p} E_{i}, j=1, \ldots l
$$

- We won't use such assumptions.


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## Example 1

- Reproducing classical Markov chains. Let $\left(X_{n}\right)$ be a Markov chain valued on $E=\{1, \ldots, N\}$ with transition matrix $P=\left(p_{i j}\right)$. Then defining

$$
V_{i j}=\sqrt{p_{i j}} E_{i j}=\sqrt{p_{i j}}\left|e_{i}\right\rangle\left\langle e_{j}\right| .
$$

after one step one can see that the quantum trajectory $\hat{x}_{n}$ is valued in $\left\{e_{i}, i=1, \ldots, k\right\}$.

- If the Markov chain $\left(X_{n}\right)$ is irreducible and aperiodic then the quantum trajectory ( $\hat{x}_{n}$ ) converges in law to the invariant measure

$$
\sum_{i=1}^{\ell} \pi(i) \delta_{e_{i}}
$$

where $\pi()=.(\pi(i))_{i=1, \ldots, l}$ denote the unique invariant measure of $\left(X_{n}\right)$.

- Note that the matrices $V_{i j}$ are non invertible


## Example 2

- Let $V_{1}=\left(\begin{array}{cc}\frac{1}{\sqrt{3}} & 0 \\ 0 & \frac{1}{2}\end{array}\right)$ and $V_{2}=\left(\begin{array}{cc}0 & \frac{\sqrt{3}}{2} \\ \frac{\sqrt{2}}{\sqrt{3}} & 0\end{array}\right)$

$$
\begin{aligned}
& e_{1} \mapsto\left\{\begin{array}{l}
e_{1} \text { with probability } \frac{1}{3} \\
e_{2} \text { with probability } \frac{2}{3}
\end{array}\right. \\
& e_{2} \mapsto\left\{\begin{array}{l}
e_{1} \text { with probability } \frac{1}{4} \\
e_{2} \text { with probability } \frac{3}{4}
\end{array}\right.
\end{aligned}
$$

- Again it reproduces a classical Markov chain.
- if you start with $\hat{x}_{0}=(x, y)$ with $x^{2}+y^{2}=1$

$$
(x, y) \mapsto\left\{\left\{\begin{array}{l}
\left(\frac{\frac{1}{\sqrt{3}} x}{\sqrt{\frac{1}{3} x^{2}+\frac{1}{4} y^{2}}}, \frac{\frac{1}{2} y}{\sqrt{\frac{1}{3} x^{2}+\frac{1}{4} y^{2}}}\right) \text { with probability } \frac{1}{3} x^{2}+\frac{1}{4} y^{2} \\
\left(\frac{\frac{\sqrt{3}}{2} y}{\sqrt{\frac{2}{3} x^{2}+\frac{3}{4} y^{2}}}, \frac{\frac{\sqrt{3}}{\sqrt{3}} x}{\sqrt{\frac{2}{3} x^{2}+\frac{3}{4} y^{2}}}\right) \text { with probability } \frac{2}{3} x^{2}+\frac{3}{4} y^{2}
\end{array}\right.\right.
$$

- Note that the matrices $V_{i}$ are non strongly irreducible.


## Example 2 bis

- Let $V_{1}=\left(\begin{array}{cc}\frac{1}{\sqrt{2}} & 0 \\ 0 & \frac{1}{\sqrt{2}}\end{array}\right)$ and $V_{2}=\left(\begin{array}{cc}0 & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & 0\end{array}\right)$

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$$

- Again it reproduces a classical Markov chain.
- The uniform measure is invariant

- But also

$$
\delta_{\frac{1}{\sqrt{2}}\left(e_{1}+e_{2}\right)}
$$

is also invariant

- Note that nurification is not satisfied since $V_{i}^{*} V_{i}=\frac{1}{2} / d$.


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- Note that purification is not satisfied since $V_{i}^{*} V_{i}=\frac{1}{2} l d$.


## Example 3

- Let $V_{1}=\frac{1}{\sqrt{3}}\left(\begin{array}{ll}1 & 1 \\ 0 & 1\end{array}\right)$ and $V_{2}=\frac{1}{\sqrt{3}}\left(\begin{array}{cc}1 & 0 \\ -1 & 1\end{array}\right)$
- It does not reproduce any classical Markov chain on a finite set
- Note that since $V_{1}$ and $V_{2}$ are real it preserves real vectors
- Simulations show that the invariant measure has full support on the set of real vectors
- Remark: The support of invariant measure is a tedious question. In the classical setup of product of i.i.d random matrices, knowing if it is absolutely continuous with respect to the Lebesgue measure is still an open question.


## 2) Invariant Measure

## (1) The probability space

- The key-martingale
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## Assumptions

- Our aim: To show that there exist a unique invariant measure
- Two conditions
(1) Pur: The only projectors $Q$ statisfying $Q V_{i}^{*} V_{i} Q=\lambda_{i} Q, i=1, \ldots, l$ are rank one projectors.
(2) Irr: There exists a unique minimal projector $Q$ such that

$$
V_{i} Q\left(\mathbb{C}^{k}\right) \subset Q\left(\mathbb{C}^{k}\right), i=1, \ldots, \ell
$$

- The condition (Irr) is equivalent to the fact that the quantum channel $\phi$ has a unique invariant state. We denote $\rho_{\text {inv }}$ this state

$$
\phi\left(\rho_{\text {inv }}\right)=\rho_{i n v}
$$

## Theorem <br> Assume (Pur) and (Irr), the Markov kernel associated to $\left\{V_{i}\right\}$ has a unique invariant measure denoted $\nu_{\text {inv }}$ on $P\left(\mathbb{C}^{k}\right)$.

- Note that all the good previous examples satisfy (Pur) and (Irr)


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- Note that all the good previous examples satisfy (Pur) and (Irr).


## Probability space

- The probability space is composed of two parts, the evolution of the quantum trajectory $\hat{x}_{n}$ and the results of measurements.
- Let $\mathcal{A}=\{1, \ldots, \ell\}$ and $\Omega:=\mathcal{A}^{\mathbb{N}}$. Let $\left(\mathcal{F}_{n}\right)_{n}$ be the filtration generated by the cylinder sets $\Lambda_{I_{n}}=\Lambda_{i_{1}, \ldots, i_{n}}=\left\{\omega \in \Omega \mid \omega_{1}=i_{1}, \ldots, \omega_{n}=i_{n}\right\}$ and let $\mathcal{F}$ be the smallest $\sigma$-algebra such that $\mathcal{F}_{n} \subset \mathcal{F}$ for all $n \in \mathbb{N}$.

$\square$


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- Let $\mathcal{G}=\mathcal{F} \otimes \mathcal{B}$, then $\left(\Omega \times P\left(\mathbb{C}^{d}\right), \mathcal{G}\right)$ is a measurable compact space.
- Set $\mathcal{G}_{\mathcal{F}}=\mathcal{F} \times\left\{\emptyset, P\left(\mathbb{C}^{d}\right)\right\}$. Then any $\mathcal{G}$ measurable function such that $f(\omega, \hat{x})=f(\omega, \hat{y})$ for any $\omega \in \Omega$ and $\hat{x}, \hat{y} \in P\left(\mathbb{C}^{k}\right)$ is $\mathcal{G}_{\mathcal{F}}$-measurable. There is a natural embedding of $\mathcal{F}$ measurable functions into $\mathcal{G}_{\mathcal{F}}$-measurable functions setting $f: \omega, \hat{x} \mapsto f(\omega)$.
- Let $\nu$ be a probability measure over $\left(P\left(\mathbb{C}^{d}\right), \mathcal{B}\right)$. We extend it to a measure $\mu_{\nu}$ over $\left(\Omega \times P\left(\mathbb{C}^{d}\right), \mathcal{G}\right)$ setting, for any $A \in \mathcal{B}$ and any $I_{n} \in \mathcal{A}^{n}$,


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- Let $\mathcal{A}=\{1, \ldots, \ell\}$ and $\Omega:=\mathcal{A}^{\mathbb{N}}$. Let $\left(\mathcal{F}_{n}\right)_{n}$ be the filtration generated by the cylinder sets $\Lambda_{I_{n}}=\Lambda_{i_{1}, \ldots, i_{n}}=\left\{\omega \in \Omega \mid \omega_{1}=i_{1}, \ldots, \omega_{n}=i_{n}\right\}$ and let $\mathcal{F}$ be the smallest $\sigma$-algebra such that $\mathcal{F}_{n} \subset \mathcal{F}$ for all $n \in \mathbb{N}$.
- Let $\mathcal{G}=\mathcal{F} \otimes \mathcal{B}$, then $\left(\Omega \times P\left(\mathbb{C}^{d}\right), \mathcal{G}\right)$ is a measurable compact space.
- Set $\mathcal{G}_{\mathcal{F}}=\mathcal{F} \times\left\{\emptyset, P\left(\mathbb{C}^{d}\right)\right\}$. Then any $\mathcal{G}$ measurable function such that $f(\omega, \hat{x})=f(\omega, \hat{y})$ for any $\omega \in \Omega$ and $\hat{x}, \hat{y} \in P\left(\mathbb{C}^{k}\right)$ is $\mathcal{G}_{\mathcal{F}}$-measurable. There is a natural embedding of $\mathcal{F}$ measurable functions into $\mathcal{G}_{\mathcal{F}}$-measurable functions setting $f: \omega, \hat{x} \mapsto f(\omega)$.
- Let $\nu$ be a probability measure over $\left(P\left(\mathbb{C}^{d}\right), \mathcal{B}\right)$. We extend it to a measure $\mu_{\nu}$ over $\left(\Omega \times P\left(\mathbb{C}^{d}\right), \mathcal{G}\right)$ setting, for any $A \in \mathcal{B}$ and any $I_{n} \in \mathcal{A}^{n}$,

$$
\mu_{\nu}\left(I_{n} \times A\right):=\int_{A}\left\|V_{I_{n}} \hat{x}\right\|^{2} d \nu(\hat{x})
$$

with $V_{l_{n}}=V_{i_{n}} \cdots V_{i_{2}} V_{i_{1}}$.

## Probability space

- Let $\hat{y} \in P\left(\mathbb{C}^{d}\right)$ be fixed. Let the sequence $\left(\hat{x}_{n}\right)_{n \in \mathbb{N}}$ be defined by

$$
\hat{x}_{n}:=\widehat{V_{I_{n}} x}, \text { if }\left\|V_{I_{n}} x\right\| \neq 0 \quad \text { and } \quad \hat{x}_{n}:=\hat{y}, \text { else. }
$$

The second eventuality has $\mu_{\nu}$ probability 0 . The sequence $\left(\hat{x}_{n}\right)_{n}$ is a realisation on $\left(\Omega \times P\left(\mathbb{C}^{d}\right), \mathcal{G}, \mu_{\nu}\right)$ of the Markov chain defined by $\Pi$ and initial probability measure $\nu$.

- Particularly, under the law $\mu_{\nu}$, for each $n \in \mathbb{N}$, $\hat{x}_{n}$ has law $\nu \Pi^{n}$.


The marginal of $\mu_{\nu}$ restricted to $\mathcal{G}_{\mathcal{F}}$ is the probability measure $\mathbb{P}_{\rho_{\nu}}$ over $(\Omega, \mathcal{F})$
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- Particularly, under the law $\mu_{\nu}$, for each $n \in \mathbb{N}$, $\hat{x}_{n}$ has law $\nu \Pi^{n}$.


## Proposition

Let $\nu$ be a measure over $\left(P\left(\mathbb{C}^{d}\right), \mathcal{B}\right)$, we have

$$
\begin{equation*}
\mathbb{E}_{\nu}(|\hat{x}\rangle\langle\hat{x}|) \quad=\quad \rho_{\nu} \in \mathcal{D}(\mathcal{S}) \tag{1}
\end{equation*}
$$

The marginal of $\mu_{\nu}$ restricted to $\mathcal{G}_{\mathcal{F}}$ is the probability measure $\mathbb{P}_{\rho_{\nu}}$ over $(\Omega, \mathcal{F})$ :

$$
\mathbb{P}_{\rho_{\nu}}\left(I_{n}\right):=\operatorname{tr}\left(V_{l_{n}}^{*} V_{I_{n}} \rho_{\nu}\right),
$$

for any $n \in \mathbb{N}$ and any $I_{n} \in \mathcal{A}^{n}$.

## Probability space

- The last proposition implies the following one


## Proposition

Assume (Irr). For all $\nu \in \mathcal{I n v}$ we have

$$
\rho_{\text {inv }}=\mathbb{E}_{\nu}\left(\left|\hat{x}_{0}\right\rangle\left\langle\hat{x}_{0}\right|\right) .
$$

For all $\nu_{a}$ and $\nu_{b}$ in $\mathcal{I} n v$ and all $f L^{1} \mathcal{F}$-measurable random variable

$$
\mathbb{E}_{\nu_{a}}(f)=\mathbb{E}_{\nu_{b}}(f)
$$

In particular the law of $f$ does not depend on the choice $\nu \in \operatorname{Inv}$.

- The next aim is to show that $\left(\hat{x}_{n}\right)$ is close to an $\mathcal{F}$ measurable process when $n$ goes to infinity.


## The key martingale

- The key martingale is defined as follows


## Proposition

Let us consider the sequence of random variables generated by the chaotic state

$$
M_{n}:=\frac{V_{l_{n}}^{*} V_{l_{n}}}{\operatorname{tr}\left(V_{l_{n}}^{*} V_{l_{n}}\right)} \text {, if } \operatorname{tr}\left(V_{l_{n}}^{*} V_{l_{n}}\right) \neq 0 \quad \text { and } \quad M_{n}:=I_{k} / k \text {, else, }
$$

converges almost surely and in $L^{1}$-norm to a $\mathcal{G}_{\mathcal{F}}$ measurable random variable $M_{\infty}$. In particular this martingale yields the following change of measure formula

$$
\begin{equation*}
\left.\frac{d P_{\rho}}{d P_{c h}}\right|_{\mathcal{F}_{n}}=k \operatorname{tr}\left(\rho M_{n}\right),\left.\quad \frac{d P_{\rho}}{d P_{c h}}\right|_{\mathcal{F}}=k \operatorname{tr}\left(\rho M_{\infty}\right) \tag{2}
\end{equation*}
$$

Moreover, the condition (Pur) implies that there exists a $\mathcal{F}$ measurable $\hat{z}$ such that

$$
M_{\infty}=|\hat{z}\rangle\langle\hat{z}| .
$$

## The key martingale

- Recall that $\hat{x}_{n}=V_{I_{n}} \cdot \hat{x}_{0}$. Let $U_{n} D_{n}$ be the polar decomposition of $V_{I_{n}}$.
- The operator $D_{n}$ is proportional to $M_{n}^{1 / 2}$
- Let us note that

$$
\lim _{n \rightarrow \infty} M_{n}^{1 / 2} \cdot \hat{x}=\hat{z}, P_{|\hat{x}\rangle\langle\hat{x}|} \text { a.s. }
$$

Since $M_{n}$ converges to $P_{|\hat{z}\rangle\langle\hat{z}|}$ it remains to show that $\hat{x}$ is not orthogonal to $\hat{z}$. This comes from the fact that

$$
d P_{|\hat{x}\rangle\langle\hat{x}|}=k|\langle\hat{x}, \hat{z}\rangle|^{2} d P_{c h}
$$

- Introducing the natural distance

we get
$\lim _{n \rightarrow \infty} d\left(\hat{x}_{n}, U_{n} \cdot \hat{z}\right)=0$, a.s


## The key martingale

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- Introducing the natural distance

$$
d(x, y)=\sqrt{1-\frac{|\langle x, y\rangle|}{\|x\|_{2}\|y\|_{2}}}
$$

we get

$$
\lim _{n \rightarrow \infty} d\left(\hat{x}_{n}, U_{n} \cdot \hat{z}\right)=0, \text { a.s }
$$

- Remark: $\left(U_{n}\right)$ and $\hat{z}$ are $\mathcal{F}$-mesurable


## Uniqueness of the invariant measure

- This gives the uniqueness of the invariant measure


## Proposition

The set $\operatorname{Inv}$ contains a unique element denoted $\nu_{\text {inv }}$

# 3) Speed of convergence 

(1) Exponential convergence of $\mathcal{F}$ measurable functions
2. Exponential convergence towards a $\mathcal{F}$ mesurable function
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## Primitivity

- In the sequel we shall assume the following condition Prim The quantum channel is primitive, that is 1 is the only eigenvalue of modulus one (the invariant state is faithfull).
- In particular we have the following convergence


## Proposition

There exists $C>0$ and $0<\lambda<1$ such that for all $k \in \mathbb{N}^{*}$ and all $\rho \in \mathcal{D}(\mathcal{S})$

$$
\left\|\phi^{k}(\rho)-\rho_{i n v}\right\| \leqslant C \lambda^{k} .
$$

- Note that without (Prim) there still exists $m$ such that

$$
\left\|\frac{1}{m} \sum_{r=0}^{m-1} \phi^{m k+r}(\rho)-\rho_{i n v}\right\| \leqslant C \lambda^{k}
$$

## Convergence of $\mathcal{F}$ mesurable functions

- Recall the total variation distance is defined as

$$
\|\mu-\nu\|_{T V}=\sup _{A \in \mathcal{F}}|\mu(A)-\nu(A)|
$$

## Proposition

Assume (Prim). There exists $C>0,0<\lambda<1$ such that for all $\rho \in \mathcal{D}(\mathcal{S})$ and for all $n \in \mathbb{N}^{*}$

$$
\begin{align*}
& \sup _{A \in \mathcal{F}}\left|\mathbb{E}_{\phi^{n}(\rho)}\left[\mathbf{1}_{A}\right]-\mathbb{E}_{\rho_{\text {inv }}}\left[\mathbf{1}_{A}\right]\right| \leqslant C \lambda^{n}  \tag{3}\\
&\left\|\mathbb{P}_{\phi^{n}(\rho)}-\mathbb{P}_{\rho_{i n v}}\right\|_{T V} \leqslant C \lambda^{n} \tag{4}
\end{align*}
$$

- We shall use this proposition in the following form. Let $f$ be a $\mathcal{F}$ measurable function bounded by 1

$$
\begin{equation*}
\left|\mathbb{E}_{\rho}\left[f \circ \theta^{n}\right]-\mathbb{E}_{\rho_{\text {inv }}}[f]\right| \leqslant C \lambda^{n} \tag{5}
\end{equation*}
$$

where $\theta$ denotes the usual shift on $\Omega$.

## Convergence towards a $\mathcal{F}$ mesurable process

- In order to prove the exponential convergence we need to introduce a new process which is statistically close to $\hat{x}_{n}$


## Definition

For all $n \in \mathbb{N}^{*}$ and for all $I_{n} \in \mathcal{A}^{n}$ define

$$
\begin{equation*}
y_{I_{n}}=\underset{\hat{x} \in P\left(\mathbb{C}^{k}\right)}{\operatorname{argmax}}\left\{\ln \left(\mathbb{P}_{\hat{x}}\left(I_{n}\right)\right)\right\} \tag{6}
\end{equation*}
$$

and put

$$
\hat{z}_{n}=V_{I_{n}} \cdot \hat{y}_{l_{n}}
$$

- Note that $\mathbb{P}_{\hat{x}}\left(I_{n}\right)=\left\|V_{I_{n}} \hat{x}\right\|^{2}$ then

$$
\sqrt{V_{l_{n}}^{*} V_{l_{n}}} \hat{y}_{l_{n}}=a_{1}\left(V_{l_{n}}\right) \hat{y}_{I_{n}},
$$

where $a_{1}(X)$ denote the largest singular value of $X$.

- In particular $\hat{z}_{n}$ is $\mathcal{F}$ mesurable and

$$
\lim d\left(\hat{x}_{n}, \hat{z}_{n}\right)=0
$$

## Convergence towards a $\mathcal{F}$ mesurable process

- The following proposition expresses the exponential convergence towards a $\mathcal{F}$ measurable process.


## Proposition

There exists $0<\lambda<1$ and $C>0$ such that for any probability measure $\nu$ over $\left(P\left(\mathbb{C}^{k}\right), \mathcal{B}\right)$,

$$
\mathbb{E}_{\nu}\left(d\left(\hat{x}_{n}, \hat{z}_{n}\right)\right) \leqslant C \lambda^{n}
$$

More generally for any probability measure $\nu$ over $\left(P\left(\mathbb{C}^{k}\right), \mathcal{B}\right)$, for all $k \in \mathbb{N}$

$$
\begin{equation*}
\mathbb{E}_{\nu}\left(d\left(\hat{x}_{n+k}, \hat{z}_{n} \circ \theta^{k}\right)\right) \leqslant C \lambda^{n} . \tag{7}
\end{equation*}
$$

- In order to show such a result we shall use the exterior product $\wedge$ on $P\left(\mathbb{C}^{k}\right)$

$$
\begin{equation*}
d(\hat{x}, \hat{y})=\frac{\|x \wedge y\|}{\|x\|\|y\|} . \tag{8}
\end{equation*}
$$

## Convergence towards a $\mathcal{F}$ mesurable process

- First we remark that

$$
d\left(\hat{x}_{n}, \hat{z}_{n}\right)=d\left(V_{l_{n}} \cdot \hat{x}, V_{l_{n}} \cdot \hat{y_{n}}\right)=\frac{\left\|\wedge^{2} V_{I_{n}} x \wedge y_{I_{n}}\right\|}{\left\|V_{I_{n}} x\right\|\left\|V_{I_{n}}\right\|} \leqslant \frac{\left\|\wedge^{2} V_{l_{n}}\right\|}{\left\|V_{I_{n}} x\right\|^{2}}
$$

- Next we show that

$$
\mathbb{E}_{\nu}\left(\frac{\left\|\wedge^{2} V_{I_{n}}\right\|}{\left\|V_{I_{n}} x\right\|^{2}}\right) \leqslant \sum_{I_{n} \in \mathcal{A}^{n}}\left\|\wedge^{2} V_{l_{n}}\right\|
$$

- In fact

$$
f(n)=\sum_{I_{n} \in \mathcal{A}^{n}}\left\|\wedge^{2} V_{I_{n}}\right\|=\mathbb{E}_{c h}\left[\frac{\left\|\wedge^{2} V_{l_{n}}\right\|}{P_{c h}\left[I_{n}\right]}\right]
$$

defines a sub-multiplicative function which tends to 0 when $n$ goes to infinity.

- Then we get

$$
\mathbb{E}_{\nu}\left(d\left(\hat{x}_{n}, \hat{z}_{n}\right)\right) \leqslant f(n) \leqslant C \lambda^{n}
$$

## Wasserstein

- Recall that the Wassersein distance can be viewed as

$$
W_{1}(\mu, \nu)=\sup _{f \in L i p(1)}\left|\int_{\Omega} f d(\mu-\nu)\right|,
$$

- Let $f \in \operatorname{Lip}\left(1, P\left(\mathbb{C}^{k}\right)\right)$, let $n \in \mathbb{N}^{*}$. We shall distinguish the case where $n=2 k$ and $n=2 k+1$. Let us start with the case where $n=2 k$, we have

$$
\begin{aligned}
& \left|\mathbb{E}_{\nu}\left[f\left(\hat{x}_{n}\right)\right]-\mathbb{E}_{\nu_{\text {inv }}}[f(\hat{x})]\right| \\
\leqslant & \left|\mathbb{E}_{\nu}\left[f\left(\hat{x}_{2 k}\right)\right]-\mathbb{E}_{\nu}\left[f\left(\hat{z}_{k} \circ \theta^{k}\right)\right]\right|+\left|\mathbb{E}_{\nu}\left[f\left(\hat{z}_{k} \circ \theta^{k}\right)\right]-\mathbb{E}_{\nu_{\text {inv }}}\left[f\left(\hat{z}_{k} \circ \theta^{k}\right)\right]\right| \\
& +\left|\mathbb{E}_{\nu_{\text {inv }}}\left[f\left(\hat{z}_{k} \circ \theta^{k}\right)\right]-\mathbb{E}_{\nu_{\text {inv }}}\left[f\left(\hat{x}_{2 k}\right)\right]\right| \\
\leqslant & \mathbb{E}_{\nu}\left[d\left(\hat{x}_{k+k}, \hat{z}_{k} \circ \theta^{k}\right)\right]+\left|\mathbb{E}_{\rho_{\nu}}\left[f\left(\hat{z}_{k} \circ \theta^{k}\right)\right]-\mathbb{E}_{\rho_{\text {inv }}}\left[f\left(\hat{z}_{k} \circ \theta^{k}\right)\right]\right| \\
& +\mathbb{E}_{\nu_{\text {inv }}}\left[d\left(\hat{x}_{k+k}, \hat{z}_{k} \circ \theta^{k}\right)\right]
\end{aligned}
$$

- Conclusion $W_{1}\left(\nu \Pi^{n}, \nu_{\text {inv }}\right) \leqslant C \lambda^{n}$


## Conclusion

## Remarks

- In parallel to the study of the Markov chain ( $\hat{x}_{n}$ ) one can also study the process $\left(X_{n}\right)$ valued in $\{1 \ldots, \ell\}$ which corresponds to the index $i$ corresponding to the transition $V_{i}$ such that $\hat{x}_{n+1}=V_{i} \cdot \hat{x}_{n}$. This process is attached to the so-called measurement records. In particular $N_{n}(i)=\sum \mathbf{1}_{i}\left(X_{n}\right)$ correspond to the number of occurrence of $i$. It represents the number of times where we have observed the result $i$.
- The process $\left(X_{n}\right)$ is not a Markov chain but the process $\left(\hat{x}_{n}, X_{n}\right)$ is. In particular we have the following theorem concerning the invariant measure and the convergence towards this measure


## Proposition

Assume ... Let $\nu_{i n v}$ be the invariant measure of $\left(\hat{x}_{n}\right)$. Then $\left(\hat{x}_{n}, X_{n}\right)$ has a unique invariant measure denoted by $\tilde{\nu}_{\text {inv }}$ defined by

$$
\mathbb{E}_{\tilde{\nu}_{\text {inv }}}[f(\hat{x}, X)]=\sum_{i} \int_{\Omega} f(\hat{x}, i)\left\|V_{i} \hat{x}\right\|^{2} d \nu_{\text {inv }}(\hat{x})
$$

## Works in progress

- We get the law of large numbers


## Theorem (Strong Law of Large Numbers)

Assume (Irr) and (Pur) hold. Assume $f$ is continuous. Let $\nu$ be a measure over $\left(P\left(\mathbb{C}^{k}\right), \mathcal{B}\right)$. Then,

$$
\lim _{t \rightarrow \infty} \frac{1}{n} S_{n}(f)=\nu_{\text {inv. }}(f) \quad \mu_{\nu}-\text { a.s. }
$$

- The above LLN generalizes the mean Cesaro result of H . Maasen and $B$. Kümmerer.
- The CLT for a class of $\alpha$ Hölder functions.
- LDP.
- Spectral study of $\Pi$.
- Open question: support of $\nu_{\text {inv }}$.
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## Thank You

